



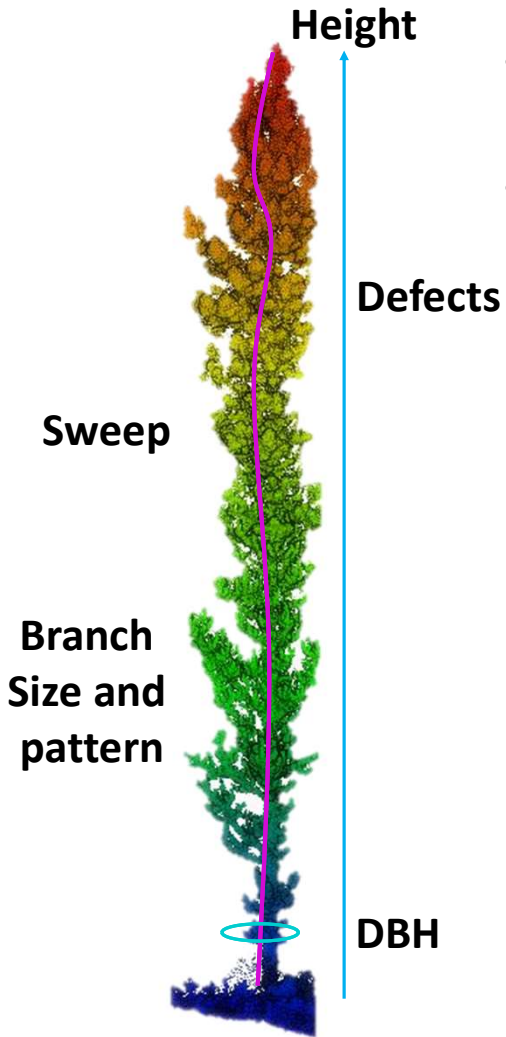
Towards autonomy: Tree form phenotyping pipeline

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What is Phenotyping and why should we automate it?

- Compare tree form with genetics, environment and silviculture (GxExS) to identify optimal trees for a given situation.
- Uses: Tree breeding and Forest Management (Right Tree, Right Place, Right Purpose).



Traditional Measurement

- Time consuming/costly,
- Subjective
- Plot-based metrics - Averaging
- Bias (tree heights - occlusion, terrain effects, tree lean...)
- Low throughput



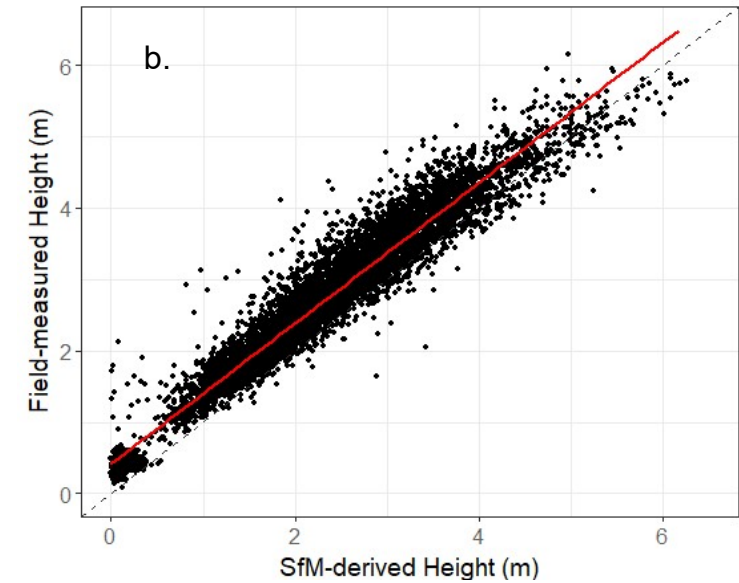
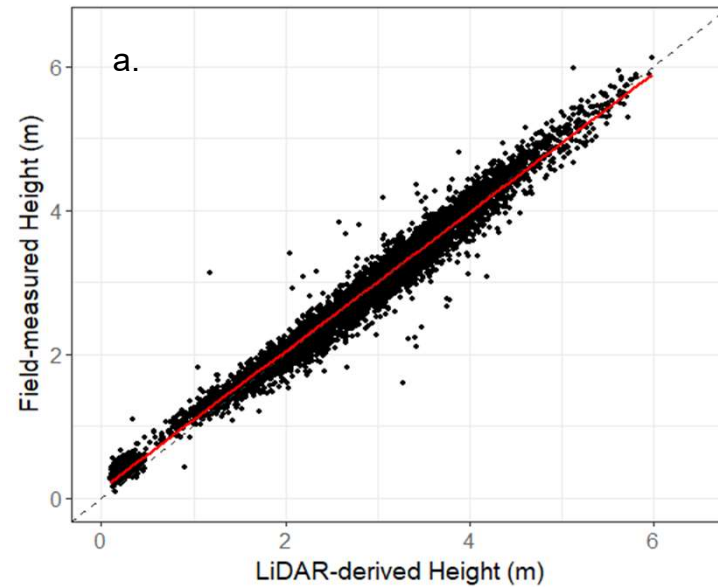
Automated

- Rapid
- Objective
- Individual tree
- Less-biased
- High throughput

Backstory:



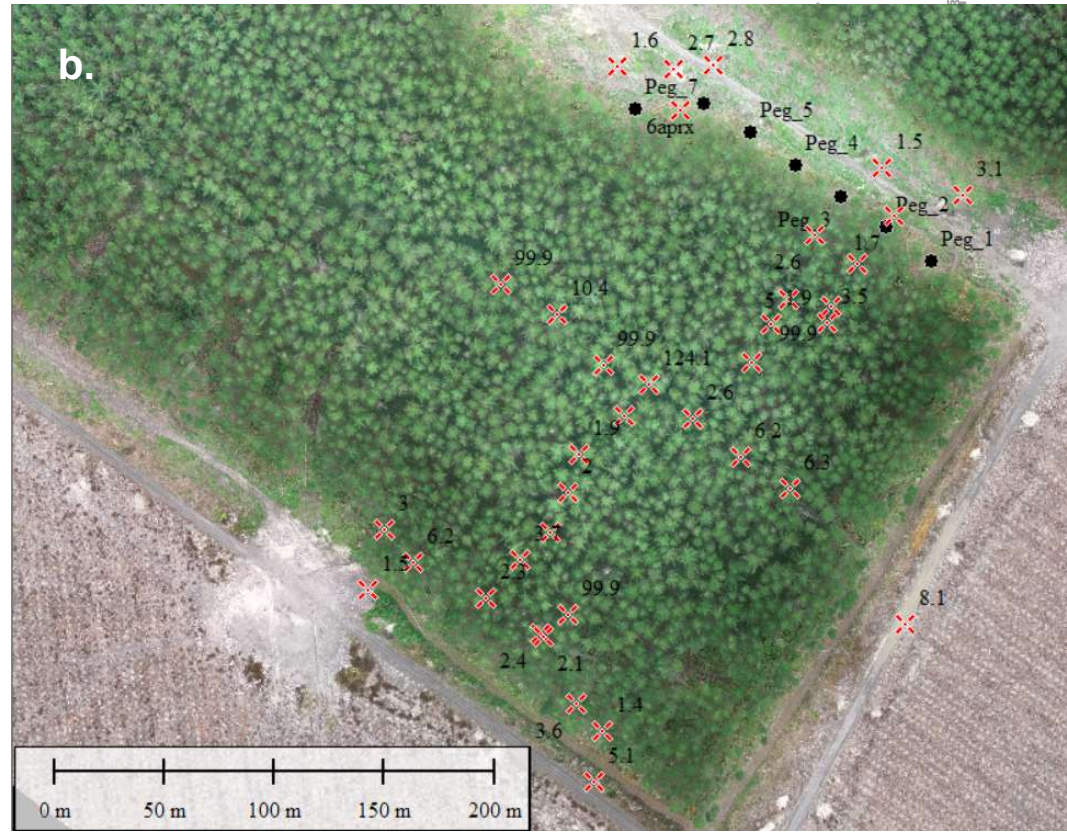
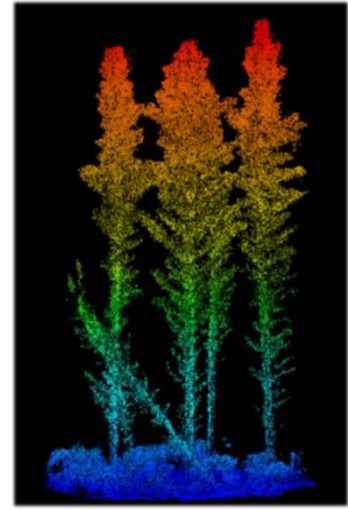
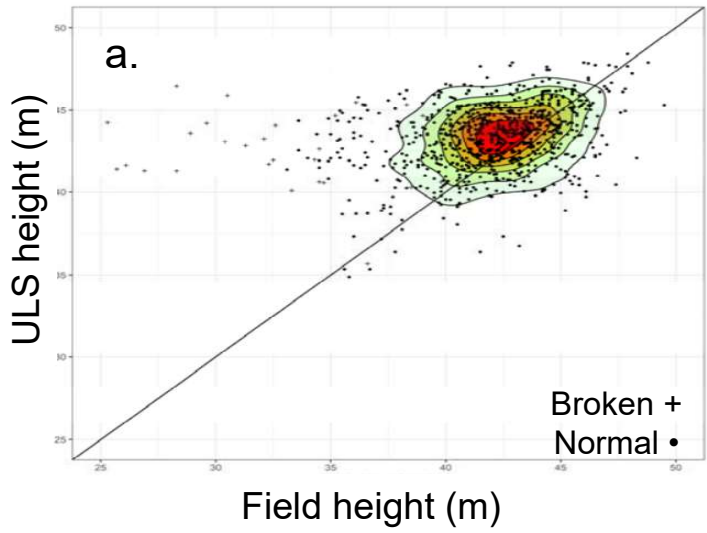
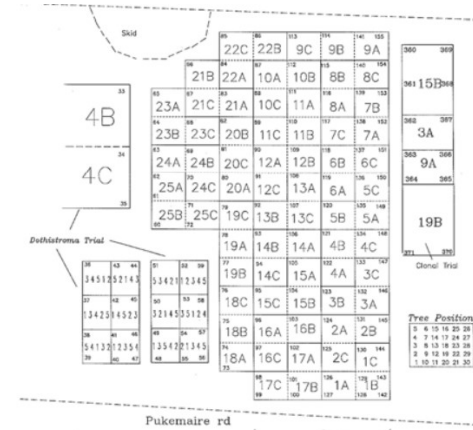
- GCFF: can we measure trees with UAVs?
 - UAV laser scanning (ULS) (MiniVUX1-UAV)
 - Photogrammetry (SfM) (DJI Phantom 4 pro – used by industry)
- 6 trial sites across NZ North Island, age 4 months to age 3.
- SfM and ULS both highly accurate for heights in young trials



Backstory contd...

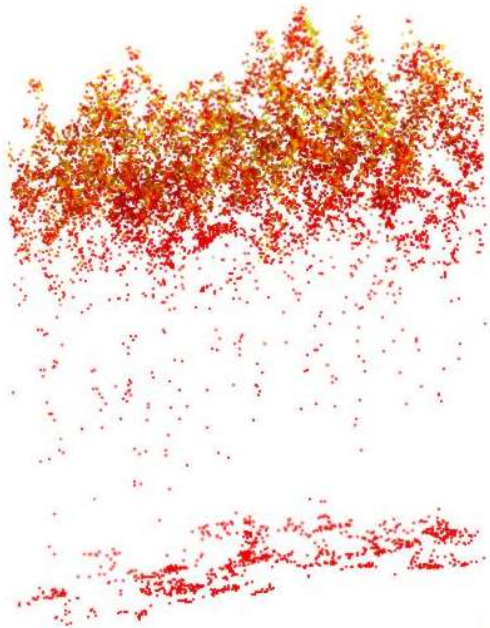
- 26 year old, pre-harvest breeding trial
- ULS from MiniVUX – 1,589 ppm²
- Heights from field and ULS didn't line up well (a)
- Lining up plots with ground truth very difficult (b)
- Started to think we needed to go sub-canopy to get a better trial map

Dash, J. P., Watt, M. S. and Hartley, R. J. L. (2019) Testing UAV-borne Riegl Mini VUX-1 scanner for phenotyping a mature genetics trial. *Technical Notes from the Growing Confidence in Forestry's Future Research Programme TN-023*. <https://scionforestryfuture.files.wordpress.com/2022/07/gcff-tn023.pdf>

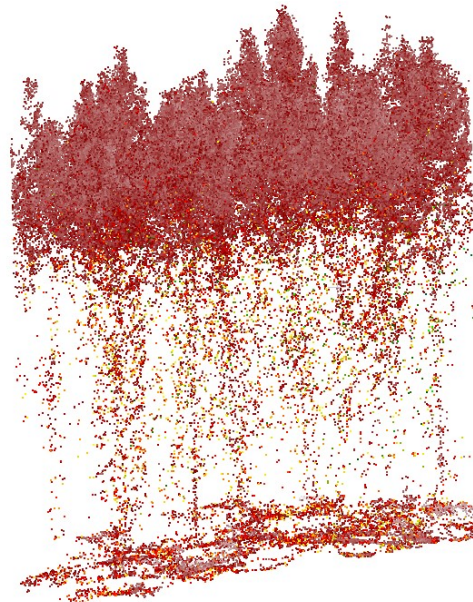


Why is sub-canopy better for single tree phenotyping?

- Scion has researched the use of airborne laser scanning (ALS) and ULS for forest characterisation and phenotyping for many years (Bombrun, et al., 2020; Hartley, et al., 2020; Pont, et al., 2020; Watt, et al., 2013, 2014).
- Scanning from above: very restricted for scanning stems due to the dense forest canopy.
- Sub-canopy scanning is the opposite effect: dense stem scans but less canopy definition.



ALS – 20 ppm²



ULS – 350 ppm²



MLS – 22,000 ppm²



emesent
Hovermap



SLAM (Simultaneous Localisation and Mapping) algorithms build a virtual environment from the lidar points, which then best predicts the scanner's current location, enabling navigation whilst mapping the environment

Differences with scanners

GNSS/INS: relies on GPS signal to locate the scanner in the real world, and subsequently build a point cloud through post-processing



System	Weight (kg)	Autonomous flight options	Beam footprint at 100m (cm)	No. Returns	Max measurement range (m)
Riegl MiniVUX-1 UAV	2.9	Above only	1.6 x 0.5	5	150 (120m)
Emesent Hovermap	1.8	Above / Below	28.7 x 16	2	100 (50-70m)



RIEGL miniVUX-1 UAV

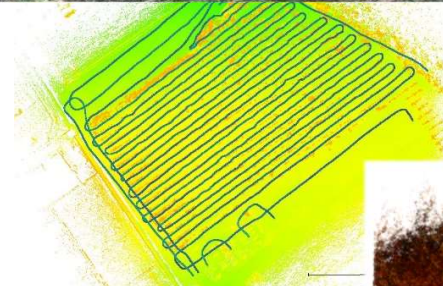
Sub-canopy: comparison of methods

- Backpack: Point density ~22,000 ppm²
- Semi-autonomous (AL1): manually flying with industrial-grade object avoidance
- Fully Autonomous (AL2): waypoint-based flight

System	Time to capture (hrs:mins)	Number of scan files created	Time to process (hrs:mins)	Time to merge (hrs:mins)	Total time (hrs:mins)
Backpack	0:45	1	4:00	NA	4:45
Semi-autonomous	2:30	19	2:15	4:00	9:00
Fully autonomous	12:30	40	11:15	4:30	28:15

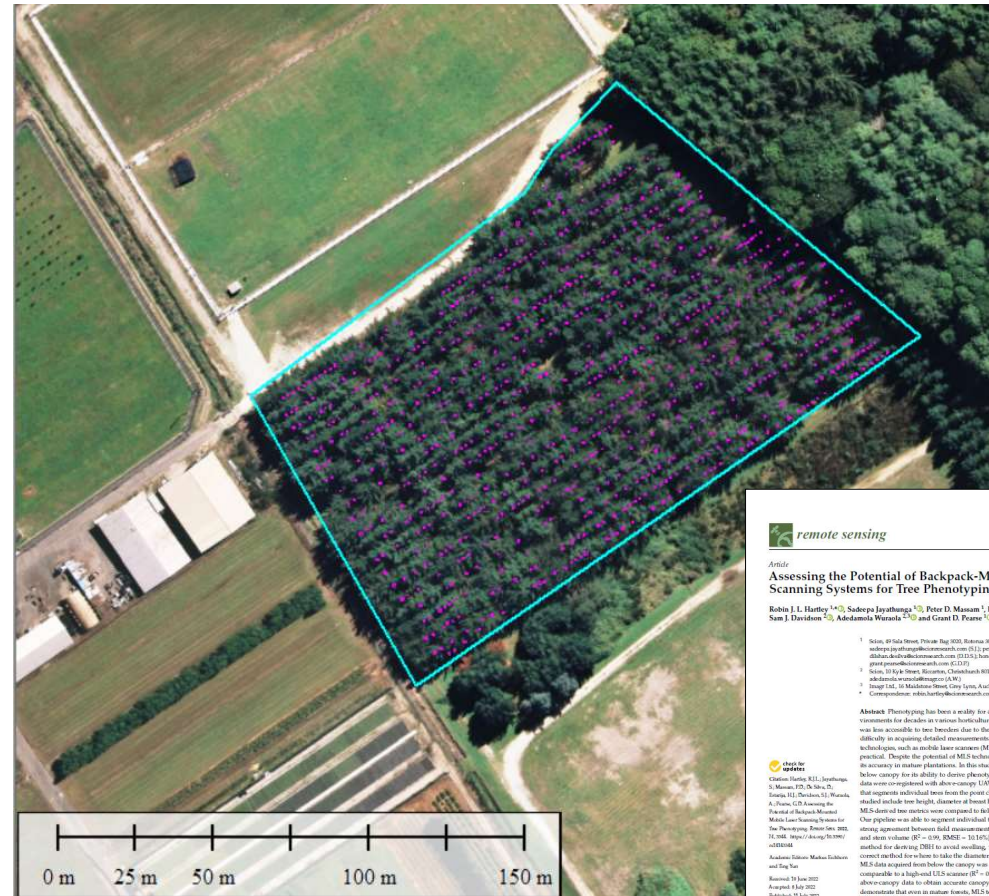
* Trial area of 4 rows: results multiplied x5 to estimate total area coverage lines.

- At this stage backpack is by far the most efficient
- UAV limited by battery – more efficient crafts now available.



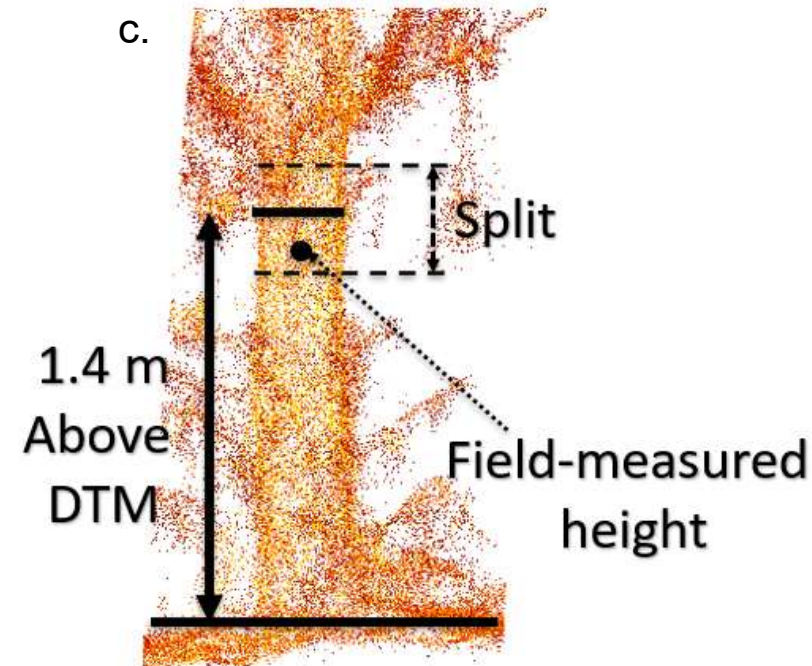
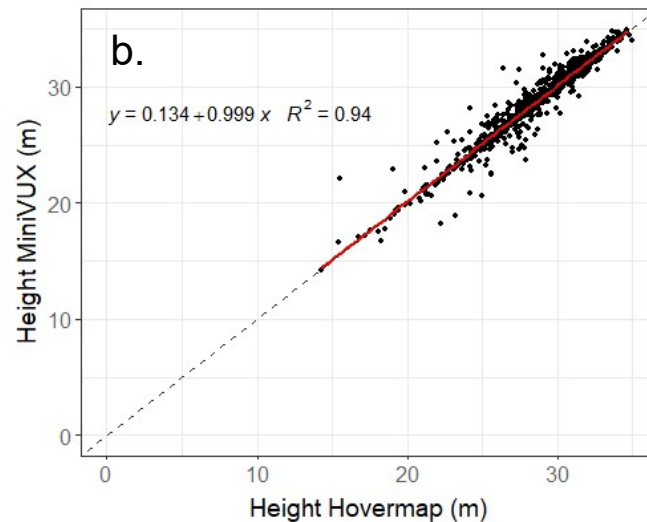
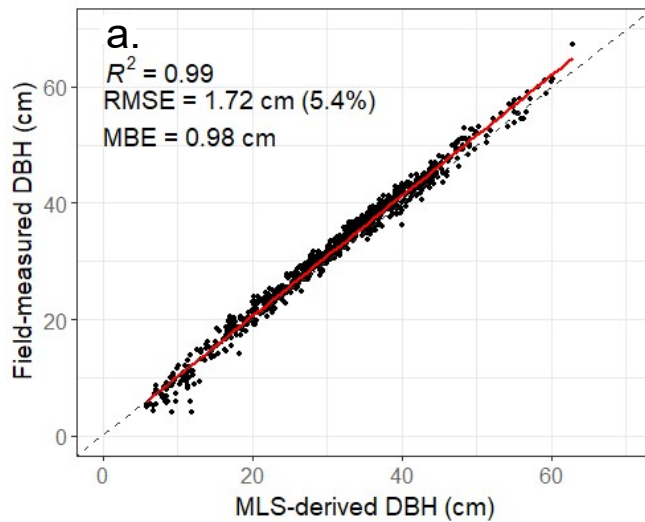
Study 1: Backpack scanning for Phenotyping

- Explored Hovermap in a mature genetics archive at Scion
 - 884 trees
 - Age 20-21
 - DBH: 2-67cm
 - Height 2-34 m
- Inventory (full cruise: DBH, height etc)
- Climbed and measured subset of 12 trees
 - Branching
 - Stem curve
- Published results in top tier journal



Findings from study 1

- DBH – can be derived with high precision and accuracy
 - $R^2 = 0.99$, RMSE = 1.72 cm (5.4%)
- Introduced new method for deriving DBH
 - Based on variable height method from PLOTSAFE
- Individual tree heights not highly accurate (suppressed trees)
- Hovermap capable of reaching canopy top:
 - Compared to MiniVUX: $R^2 = 0.94$ / RMSE = 0.87 m (3%)

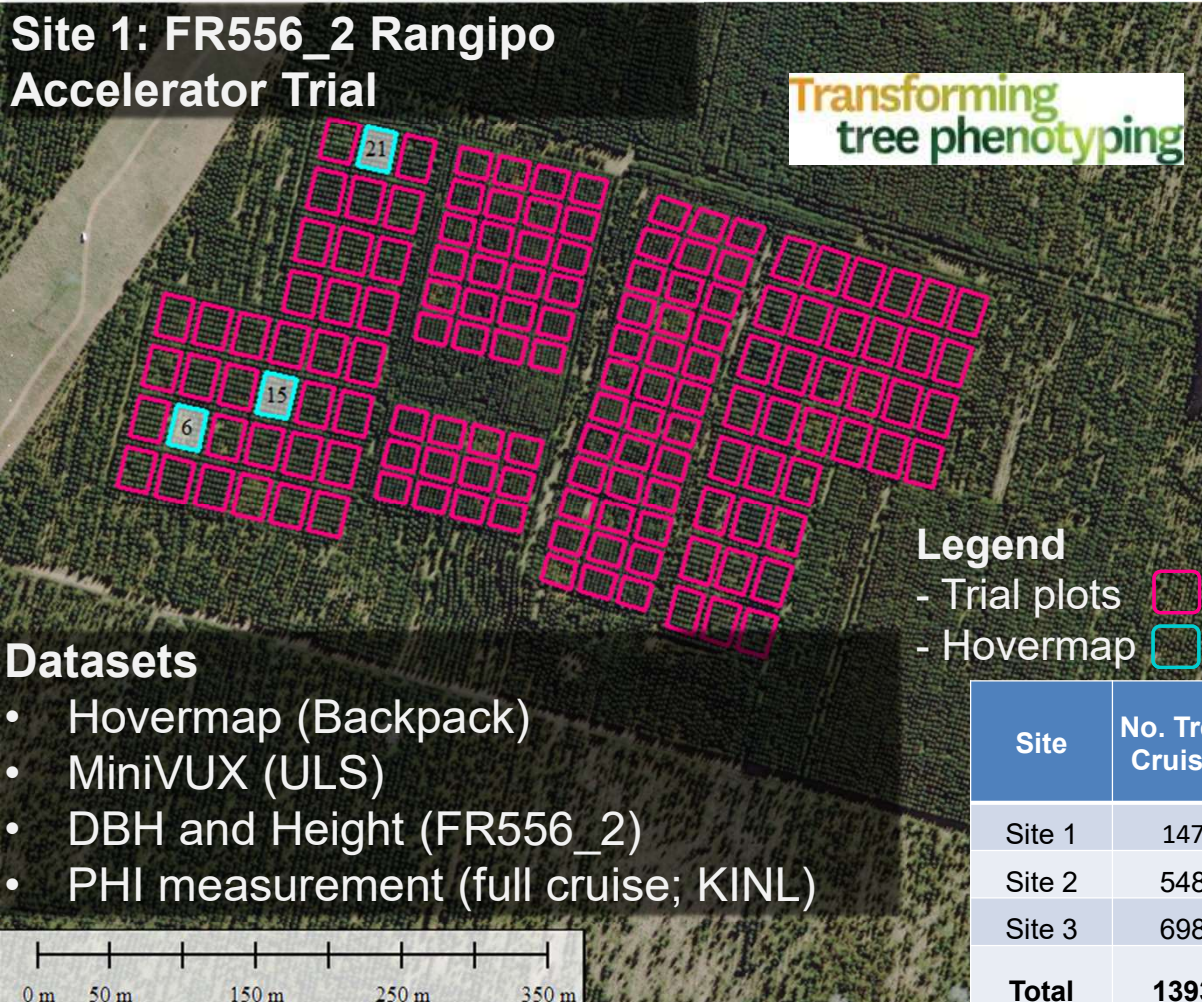


Conclusions from study 1

- Hovermap is very promising, however, needed testing in more complex environments
 - Younger/smaller trees
 - More “realistic” pre-harvest stand (slope, undergrowth, regular spacing)
- Major limitations
 - Stem volume algorithm only detects stems up to mean height of 13 m
 - Dense branching / occlusion of stem
 - Tree heights potentially accurate, but unable to detect suppressed/sub-dominant trees
 - Need a different method to find tree tops
 - Less accurate on smaller diameters (<15 cm)

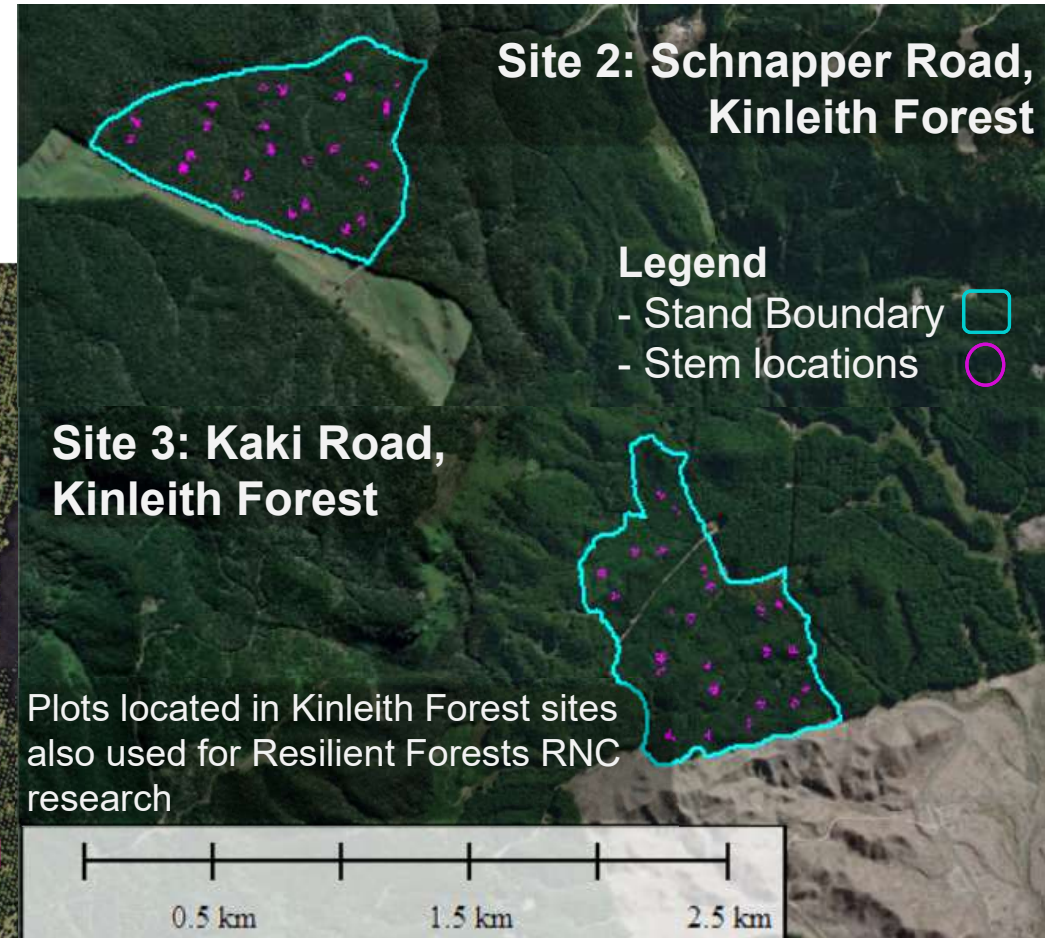
Collected more data

Site 1: FR556_2 Rangipo Accelerator Trial



Datasets

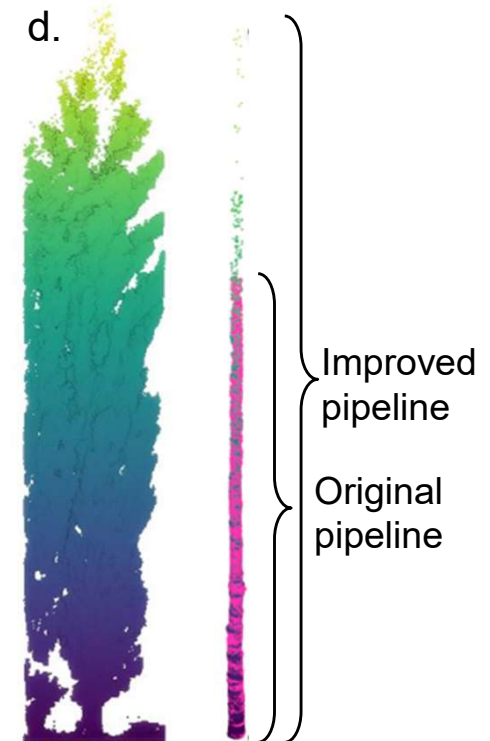
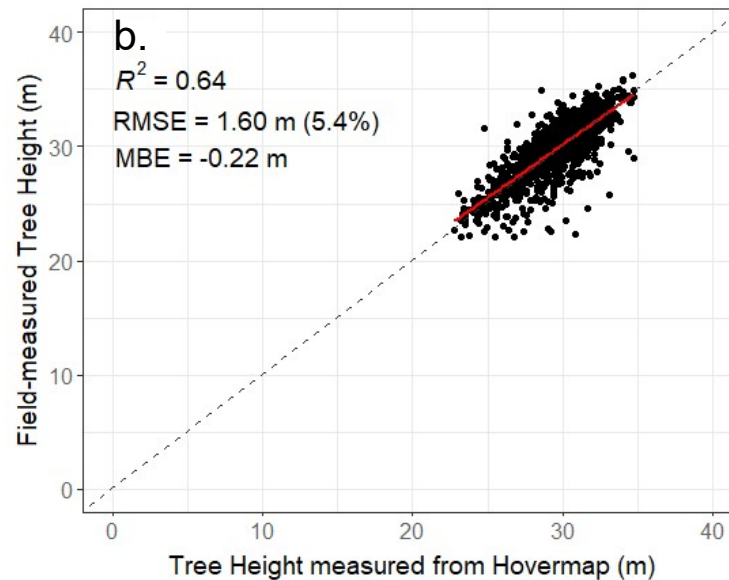
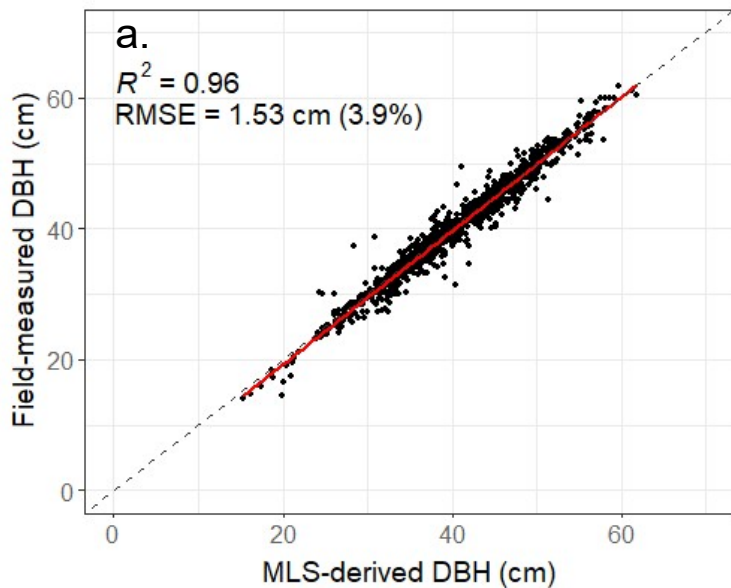
- Hovermap (Backpack)
- MiniVUX (ULS)
- DBH and Height (FR556_2)
- PHI measurement (full cruise; KINL)



Site	No. Trees Cruised	DBH Range (cm)	Mean DBH (cm)	Tree Height Range (m)	Mean Tree Height (m)	Age (yrs)	Stand size (ha)	Plots (0.06 ha)
Site 1	147	5.1-21.9	16.3	4.3-13.4	10.1	6	20	3
Site 2	548	22.2-62.2	44.1	17-36.3	30.5	18	66	24
Site 3	698	13.3-55.7	35.5	5.5-35.3	28.3	21	66	24
Total	1393	5.1-62.2	36.9	4.3-36.3	27.2	6-21	20-66	51

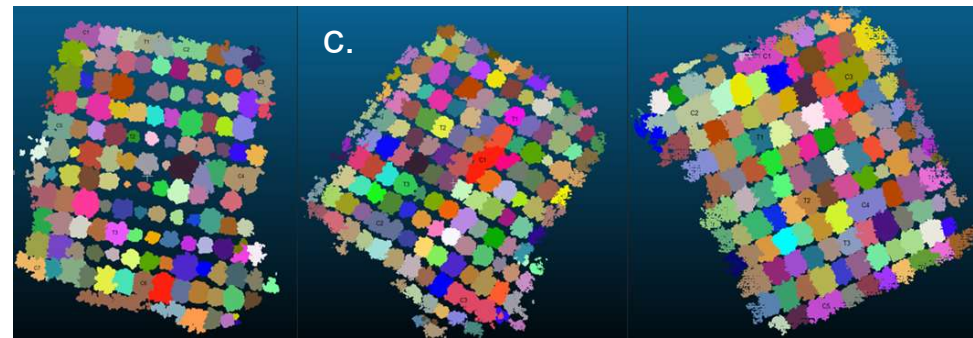
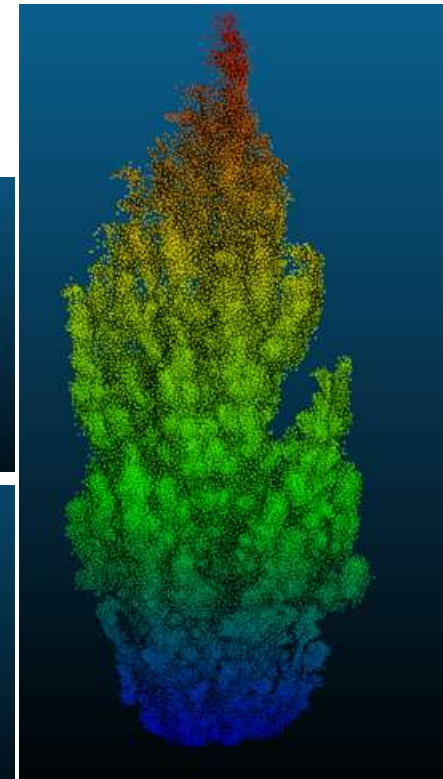
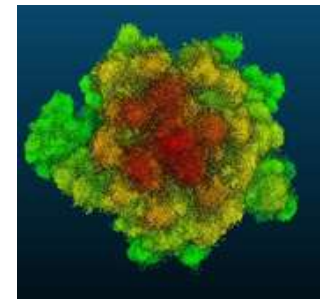
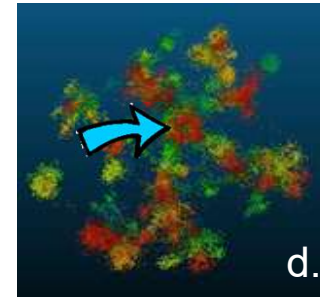
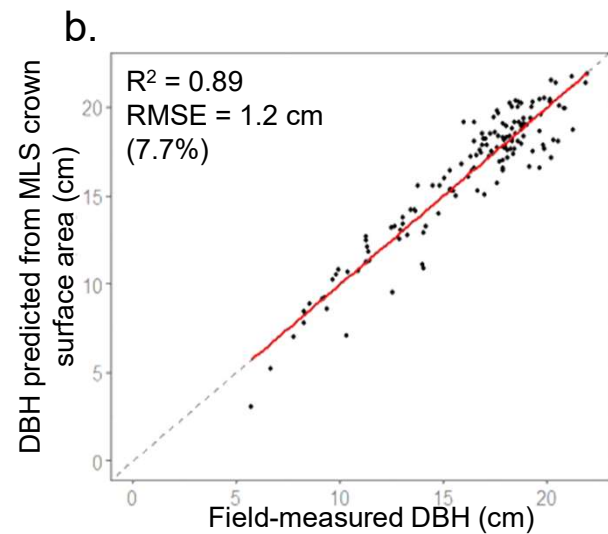
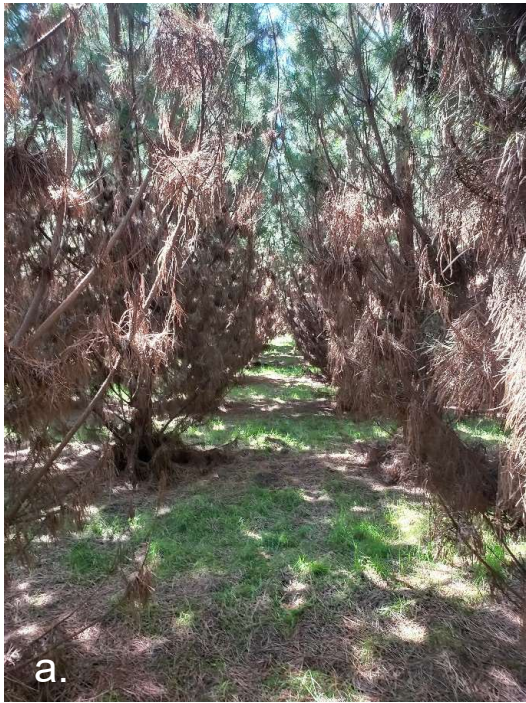
Study 2: MLS for mature plantations

- Site: Managed plantation forest with heavy understorey (c)
- Increased point coverage along the stem (d)
- Improved tree segmentation and stem delineation (d)
- Precise stem diameter predictions (RMSE = 1.5 cm, 3.9%; a)
 - Slight improvement on previous study
- Moderate-level accuracy for tree height (b)
 - Still not detecting suppressed tree peaks well



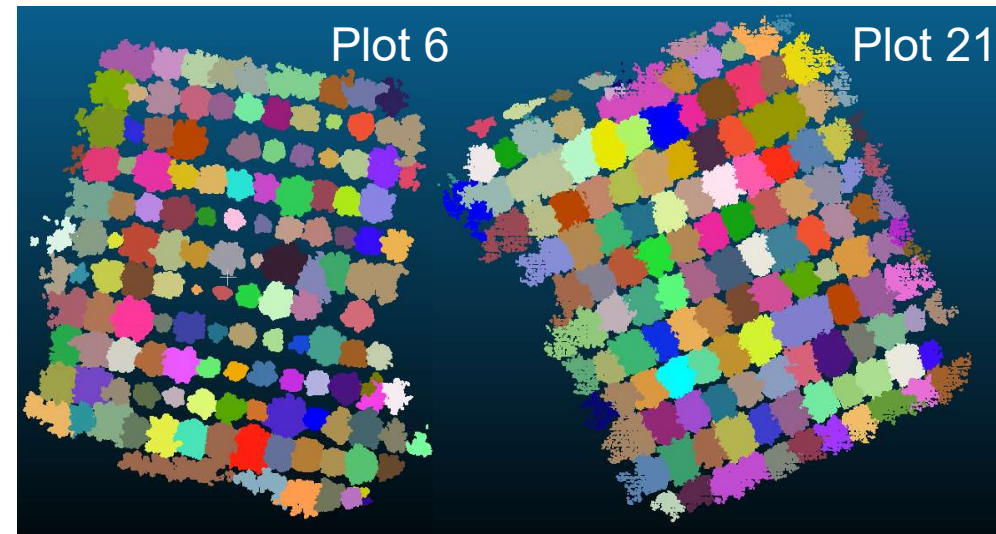
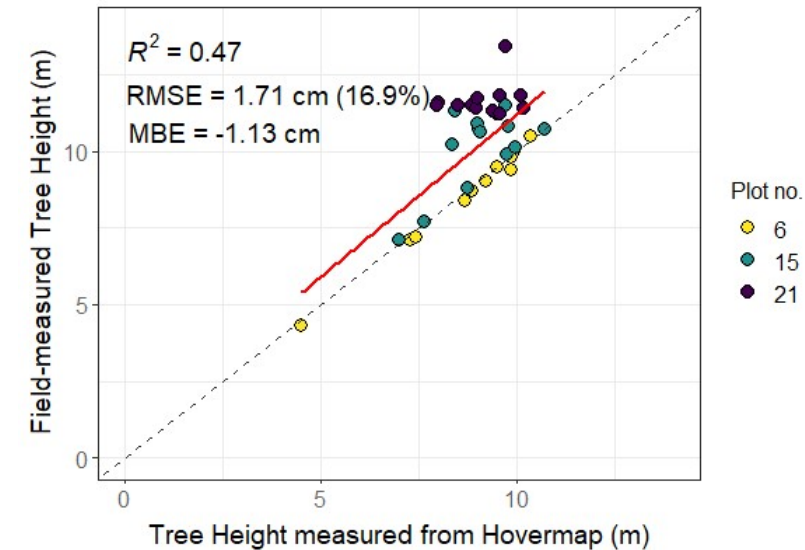
Study 3: MLS for trial selection

- Site: Young forestry trial (Rangipo accelerator trial: Age 6; a)
- Successful tree segmentation (> 97% accuracy; c)
- Inadequate laser points for stem level phenotyping (d)
- Accurate crown size estimations
- Precise modelling of diameter using crown dimensions (b)



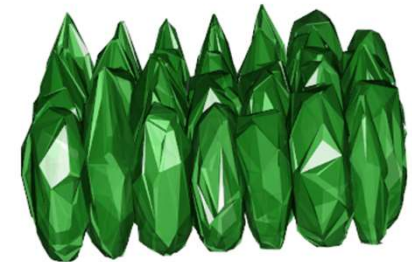
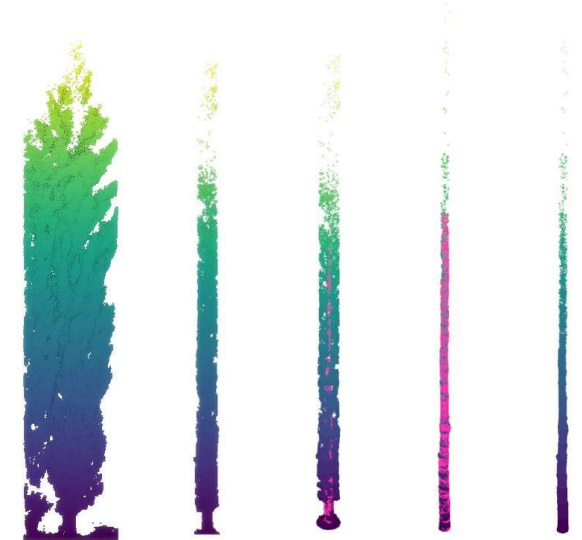
Study 3: MLS heights for trial selection

- Field measurements on 16 heights per plot
- Overall precision and accuracy are moderate:
 - $R^2 = 0.47$ / RMSE = 1.7 m (16.9%)
- Dependent on how open canopy is:
 - Open (Plot 6): $R^2 = 0.99$ / RMSE = 0.22 m (2.5%)
 - Closed (Plot 21): $R^2 = 0.04$ / RMSE = 2.6 m (22.1%)
- For height, previous study with the MiniVUX found
 - $R^2 = 0.99$, RMSE = 0.15m (5.9%) for height
- Indicates that ULS is probably better for measuring heights on small trees where canopy is closing



Recommendations from the study 2 & 3

- Test in more complex environments ✓
- Improved algorithms able to characterise more of the stem ✓
- Trial a different method for deriving tree height detection ✓
 - Improved on previous method but more work needed
- Assess the Hovermap in more “realistic” pre-harvest stand ✓
 - Accurate and precise DBH ($R^2 = 0.96$; 3.9% RMSE)
 - Need to assess impact of site on segmentation and height
- Assess performance in young stand ✓
 - New method to predict DBH with high accuracy from crown ($R^2 = 0.89$; 7.7% RMSE)

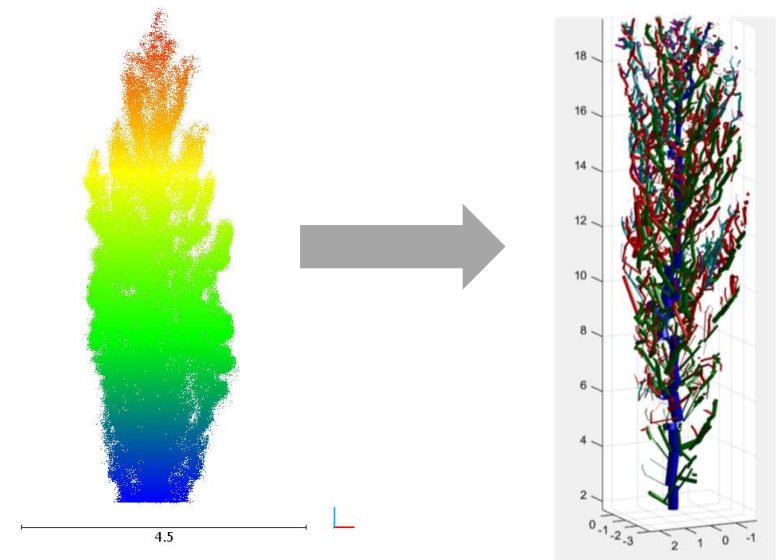


Can we use MLS to measuring branching?

- Currently studying MForSc
 - *Assessing the efficacy of MLS as a tool for branch-level phenotyping in young breeding trials of Pinus radiata.*
- Can we resolve branch-level tree form data from Hovermap?
- 2 trial sites: Age 6 and age 9
- Climbing and crown mapping a sub-sample of the trees
 - Orientation, angle, diameter and length of each branch
- Assess the following branch phenotypes:

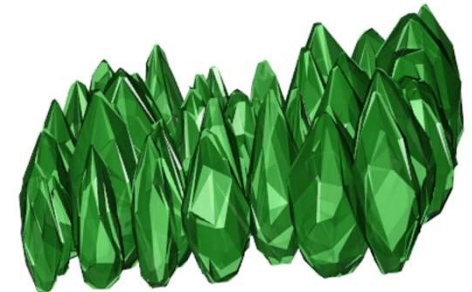


Branch Characteristic	Meaning	Unit of measurement
NB	Number of branches	n
NW	Number of whorls	n
BPW	Number of branches per whorl	n
NR	Number of ramicorn branches	n
NBM	Number of branches per tree height meter	n
MBD	Maximum branch diameter	cm
IL	Internode length	cm
BA	Branch insertion angle	degrees above horizontal



Future Research

- DBH
 - Manuscript: Accuracy of crown-derived DBH for trees ranging from <1m to 15m tall
 - Return to past datasets for MiniVUX and possibly SfM too
- Phenotyping
 - Return to mature genetics trial data
 - Apply new pipeline and attempt to phenotype trees
 - DBH, height, branch cluster frequency vs. genetics
- Branching
 - Continue Masters research to explore branch characterisation for young tree trials
 - Apply algorithms from MForSc branching research to genetics trial
 - Manuscript: Laser scanning for branch phenotyping: a review.
- Publish our pipeline for industry use



Acknowledgements

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 - Transforming Tree Phenotyping MBIE Endeavour programme for funding data capture at Rangipo Accelerator trial
 - Mike Baker and Manulife Forest Management for access to Kinleith Forest
 - Timberlands and RPBC for access to trials in Kaingaroa Forest
 - Thomas Crosse and Stephen Holdsworth at NZ Forest Managers for access to Rangipo trial and PSP measurements
 - Toby Stovold and Kane Fleet for access to Scion's Genetics Archive and their knowledge
 - Simeon Smail, Loretta Garrett and the accelerator trials team – these long-term trials have been invaluable for a number of our remote sensing studies
 - Forest & Woodlot Inventory Services team for capturing inventory data
 - Scion's Tree Biometrics and Autonomous Systems teams (and Liam Wright, formerly of Scion) for the additional trial measurements and UAV/MLS data captures



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